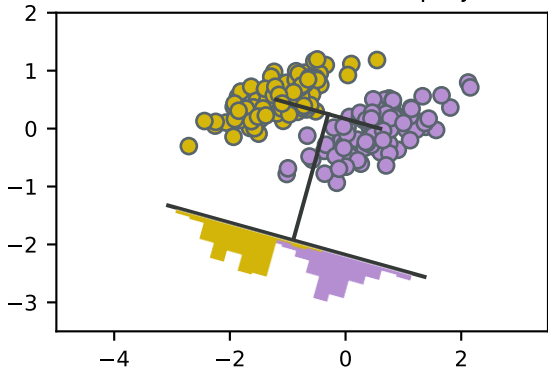


naïve projection



Fisher projection

